

Tensor decompositions in statistical signal processing

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Linear statistical model

$$\mathbf{y} = \mathbf{A}\mathbf{s} + \mathbf{b} \quad (1)$$

with

$$\left\{ \begin{array}{l} \mathbf{y} : K \times 1 \text{ random} \\ \mathbf{s} : P \times 1 \text{ random } \textit{stat. independent} \\ \mathbf{A} : K \times P \text{ deterministic} \\ \mathbf{b} : \text{errors} \end{array} \right.$$



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(may be removed for P large enough)



Other writing

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which is of the *noiseless* form

$$\mathbf{y} = \mathbf{A} \mathbf{s} \tag{2}$$

with a *larger* dimension P

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- \mathbf{A} and \mathbf{s} are jointly estimated

Application areas

- 1 Telecommunications (Cellular, Satellite, Military),
- 2 Radar, Sonar,
- 3 Biomedical (EchoGraphy, ElectroEncephaloGraphy, ElectroCardioGraphy)...
- 4 Speech, Audio,
- 5 Machine learning,
- 6 Data mining,
- 7 Control...

Identifiability & Uniqueness

- Uniqueness/Identifiability up to inherent ambiguities
- Finite number of solutions

Equivalent representations

Let \mathbf{y} admit two representations

$$\mathbf{y} = \mathbf{A} \mathbf{s} \quad \text{and} \quad \mathbf{y} = \mathbf{B} \mathbf{z}$$

where \mathbf{s} (resp. \mathbf{z}) have independent components, and \mathbf{A} (resp. \mathbf{B}) have pairwise noncollinear columns.

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- These representations are *equivalent* if every column of \mathbf{A} is proportional to some column of \mathbf{B} , and vice versa.
- If all representations of \mathbf{y} are equivalent, they are said to be *essentially unique* (permutation & scale ambiguities only).

Identifiability & uniqueness theorems

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- **Identifiability theorem** \mathbf{y} can be represented as $\mathbf{y} = \mathbf{A}_1 \mathbf{s}_1 + \mathbf{A}_2 \mathbf{s}_2$, where \mathbf{s}_1 is non Gaussian, \mathbf{s}_2 is Gaussian independent of \mathbf{s}_1 , and \mathbf{A}_1 is essentially unique.

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- **Uniqueness theorem** If in addition the columns of \mathbf{A}_1 are linearly independent, then the distribution of \mathbf{s}_1 is unique up to scale and location indeterminacies.

Example of uniqueness

Let s_i be independent with no Gaussian component, and b_i be independent Gaussian. Then the linear model below is identifiable, but \mathbf{A}_2 is not essentially unique whereas \mathbf{A}_1 is:

$$\begin{pmatrix} s_1 + s_2 + 2b_1 \\ s_1 + 2b_2 \end{pmatrix} = \mathbf{A}_1 \mathbf{s} + \mathbf{A}_2 \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} = \mathbf{A}_1 \mathbf{s} + \mathbf{A}_3 \begin{pmatrix} b_1 + b_2 \\ b_1 - b_2 \end{pmatrix}$$

with

$$\mathbf{A}_1 = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix}, \quad \mathbf{A}_2 = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} \quad \text{and} \quad \mathbf{A}_3 = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

Hence the distribution of \mathbf{s} is essentially unique.

But $(\mathbf{A}_1, \mathbf{A}_2)$ not equivalent to $(\mathbf{A}_1, \mathbf{A}_3)$.

Example of non uniqueness

Let s_i be independent with no Gaussian component, and b_i be independent Gaussian. Then the linear model below is *identifiable*, but the distribution of \mathbf{s} is not unique because a 2×4 matrix cannot be full column rank:

$$\begin{pmatrix} s_1 + s_3 + s_4 + 2b_1 \\ s_2 + s_3 - s_4 + 2b_2 \end{pmatrix} = \mathbf{A} \begin{pmatrix} s_1 \\ s_2 \\ s_3 + b_1 + b_2 \\ s_4 + b_1 - b_2 \end{pmatrix} = \mathbf{A} \begin{pmatrix} s_1 + 2b_1 \\ s_2 + 2b_2 \\ s_3 \\ s_4 \end{pmatrix}$$

with

$$\mathbf{A} = \begin{pmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & -1 \end{pmatrix}$$

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First c.f.

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- Real Multivariate: $\Phi_{\mathbf{x}}(\mathbf{t}) \stackrel{\text{def}}{=} \mathbb{E}\{e^{i \mathbf{t}^T \mathbf{x}}\} = \int_{\mathbf{u}} e^{i \mathbf{t}^T \mathbf{u}} dF_{\mathbf{x}}(\mathbf{u})$

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Second c.f.

- $\Psi(\mathbf{t}) \stackrel{\text{def}}{=} \log \Phi(\mathbf{t})$
- Properties:
 - Always exists in the neighborhood of 0
 - Uniquely defined as long as $\Phi(\mathbf{t}) \neq 0$

Characteristic functions (cont'd)

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Proof.

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- if (x, y) statistically independent, then

$$\Psi_{x,y}(u, v) = \Psi_x(u) + \Psi_y(v) \quad (3)$$

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Proof.

$$\begin{aligned} \Psi_{x,y}(u, v) &= \log[\mathbb{E}\{\exp i(ux + vy)\}] \\ &= \log[\mathbb{E}\{\exp i(ux)\} \mathbb{E}\{\exp i(vy)\}]. \end{aligned}$$

Problem posed in terms of Characteristic Functions

- If s_p independent and $\mathbf{y} = \mathbf{A} \mathbf{s}$, we have the *core equation*:

$$\Psi_y(\mathbf{u}) = \sum_p \psi_p \left(\sum_q u_q A_{qp} \right) \quad (4)$$

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- Plug $\mathbf{y} = \mathbf{A} \mathbf{s}$, in definition of $\Psi_{\mathbf{y}}$ and get

$$\Phi_{\mathbf{y}}(\mathbf{u}) \stackrel{\text{def}}{=} \mathbb{E}\{\exp \imath(\mathbf{u}^T \mathbf{A} \mathbf{s})\} = \mathbb{E}\{\exp \imath\left(\sum_{p,q} u_q A_{qp} s_p\right)\}$$

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- Since s_p independent, $\phi_{\mathbf{y}}(\mathbf{u}) = \prod_p \mathbb{E}\{\exp \iota(\sum_q u_q A_{qp} s_p)\}$

Function decomposition

Problem:

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Weierstrass (1885), Stone (1948), Hilbert (1900), Kolmogorov (1957), Sprecher (1965), Hornik (1989), Cybenko (1989)...

► But here, Ψ_y and ψ_p 's are characteristic functions.

Problem seen as non symmetric tensor decomposition

Back to core equation (4):

$$\Psi_y(\mathbf{u}) = \sum_p \psi_p \left(\sum_q u_q A_{qp} \right), \mathbf{u} \in \mathcal{G}$$

- Assumption: functions ψ_p , $1 \leq p \leq P$ admit finite derivatives up to order d in a neighborhood of the origin, containing \mathcal{G} .

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- Taking $d = 3$ as a working example:

$$\frac{\partial^3 \Psi_y}{\partial u_i \partial u_j \partial u_k}(\mathbf{u}) = \sum_{p=1}^P A_{ip} A_{jp} A_{kp} \psi_p^{(3)} \left(\sum_{q=1}^K u_q A_{qp} \right)$$

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- of the form $T_{ijkl} = \sum_p A_{ip} A_{jp} A_{kp} F_{\ell p}$, if L points $\mathbf{u}_\ell \in \mathcal{G}$.

Problem seen as symmetric tensor decomposition (1/2)

If only the origin in \mathcal{G} , i.e. $\mathbf{u}_\ell = \mathbf{0}$, then

$$C_{ijk} = \sum_p A_{ip} A_{jp} A_{kp} f_p$$

Multi-linear relation relating *cumulants*.

Problem seen as symmetric tensor decomposition (2/2)

- **Equivalent writing** (still with $d = 3$ as working example)

$$\mathbf{C} = \sum_{p=1}^P f_p \mathbf{h}(p) \otimes \mathbf{h}(p) \otimes \mathbf{h}(p)$$

where $\mathbf{h}(p) \stackrel{\text{def}}{=} p$ th column of \mathbf{A} .

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Expected rank

For an order- d symmetric tensor of dimension K

- Number of equations: $\binom{K+d-1}{d}$
- Number of unknowns: PK

For what P can one have an exact fit?

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For what P can one have an exact fit?

- “Expected rank”:

$$R(K, d) \stackrel{\text{def}}{=} \left\lceil \frac{\binom{K+d-1}{d}}{K} \right\rceil \quad (5)$$

Clebsch's statement

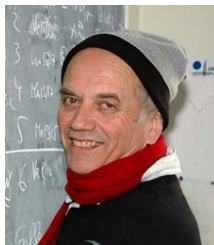


Alfred Clebsch (1833-1872)

For $(d, K) = (4, 3)$, a generic tensor cannot be written as the sum of 5 rank-1 terms, even if $\#unknowns = 15 = \#equations$

Hirschowitz theorem

From Alexander-Hirschowitz thm (1995), one deduces [CGLM08]:



THEOREM For $d > 2$, the generic rank of a d th order symmetric tensor of dimension K is **always** equal to the expected rank

$$\bar{R}_s = R(K, d) \quad (6)$$

except for $(d, K) \in \{(3, 5), (4, 3), (4, 4), (4, 5)\}$

► Only a *finite number* of exceptions !

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- *NS* condition for *almost sure* identifiability:

$$P = \frac{\binom{K+d-1}{d}}{K} = R(K, d) = \bar{R}_s$$

Generic rank of symmetric tensors

Symmetric tensors of order d and dimension K :

$d \setminus K$	2	3	4	5	6	7	8
2	2	3	4	5	6	7	8
3	2	4	5	<u>8</u>	10	12	15
4	3	<u>6</u>	<u>10</u>	<u>15</u>	21	30	42

Deterministic approaches

- Model:

$$Y_{ijk} = \sum_p A_{ip} S_{jp} B_{kp}$$

- $\mathbf{Y} = \sum_{p=1}^P \mathbf{a}(p) \otimes \mathbf{s}(p) \otimes \mathbf{b}(p)$

Expected rank

For an order- d symmetric tensor of dimensions K_ℓ , $1 \leq \ell \leq d$

- Number of equations: $\prod_\ell K_\ell$
Number of unknowns: $\sum_\ell K_\ell P - (d - 1)P$

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- Number of equations: $\prod_\ell K_\ell$
Number of unknowns: $\sum_\ell K_\ell P - (d-1)P$
- “Expected rank” again given by the ceil rule:

$$R(K_1, \dots, K_d) \stackrel{\text{def}}{=} \left\lceil \frac{\prod_\ell K_\ell}{\sum_\ell K_\ell - d + 1} \right\rceil \quad (7)$$

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- For general tensors, generic rank \bar{R} not yet known everywhere.

Generic rank of order 3 free tensors (1)

K		2				3			4	
		2	3	4	5	3	4	5	4	5
I	2	<u>2</u>	3	<u>4</u>	<u>4</u>	3	4	<u>5</u>	<u>4</u>	5
	3	3	<u>3</u>	4	<u>5</u>	<u>5</u>	5	<u>5</u>	6	<u>6</u>
	4	<u>4</u>	4	<u>4</u>	5	5	6	<u>6</u>	7	8
	5	<u>4</u>	<u>5</u>	5	<u>5</u>	<u>5</u>	<u>6</u>	8	8	9
	6	<u>4</u>	<u>6</u>	<u>6</u>	6	6	7	8	<u>8</u>	10
	7	4	<u>6</u>	<u>7</u>	<u>7</u>	<u>7</u>	<u>7</u>	9	9	<u>10</u>
	8	4	<u>6</u>	<u>8</u>	<u>8</u>	<u>8</u>	8	9	10	11
	9	4	<u>6</u>	<u>8</u>	<u>9</u>	<u>9</u>	<u>9</u>	<u>9</u>	10	12
	10	4	<u>6</u>	<u>8</u>	<u>10</u>	<u>9</u>	<u>10</u>	10	<u>10</u>	12
	11	4	<u>6</u>	<u>8</u>	<u>10</u>	<u>9</u>	<u>11</u>	<u>11</u>	11	13
	12	4	<u>6</u>	<u>8</u>	<u>10</u>	<u>9</u>	<u>12</u>	<u>12</u>	<u>12</u>	13

Perspectives

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- **Thanks for your attention**



Darmois-Skitovich theorem (1953)

Theorem

Let s_i be statistically *independent* random variables, and two linear statistics:

$$y_1 = \sum_i a_i s_i \quad \text{and} \quad y_2 = \sum_i b_i s_i$$

If y_1 and y_2 are statistically independent, then random variables s_k for which $a_k b_k \neq 0$ are Gaussian.

NB: holds in both \mathbb{R} or \mathbb{C}

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2 Write this at $u + \alpha/a_p$ and $v - \alpha/b_p$:

$$\sum_{k=1}^P \psi_k \left(u a_k + v b_k + \alpha \left(\frac{a_k}{a_p} - \frac{b_k}{b_p} \right) \right) = f(u) + g(v)$$

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- 3** Subtract to cancel P th term, divide by α , and let $\alpha \rightarrow 0$:

$$\sum_{k=1}^{P-1} \left(\frac{a_k}{a_P} - \frac{b_k}{b_P} \right) \psi_k^{(1)}(u a_k + v b_k) = f^{(1)}(u) + g^{(1)}(v)$$

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Conclusion: We have one term less

4 Repeat the procedure $(P - 1)$ times and get:

$$\prod_{j=2}^P \left(\frac{a_1}{a_j} - \frac{b_1}{b_j} \right) \psi_1^{(P-1)}(u a_1 + v b_1) = f^{(P-1)}(u) + g^{(P-1)}(v)$$

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NB: also holds if ψ_p not differentiable

Definition of Cumulants

■ Moments:

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- Relationship between Moments and Cumulants obtained by expanding both sides in Taylor series:

$$\log \Phi_x(t) = \Psi_x(t)$$

Polynomial interpolation

Alexander-Hirschowitz Theorem (1995) Let $\mathcal{L}(d, m)$ be the space of hypersurfaces of degree at most d in m variables. This space is of dimension $D(m, d) \stackrel{\text{def}}{=} \binom{m+d}{d} - 1$.

THEOREM Denote $\{p_i\}_K$ given distinct points in the complex projective space \mathbb{P}^m . The dimension of the linear subspace of hypersurfaces of $\mathcal{L}(d, m)$ having multiplicity at least 2 at every point p_i is:

$$D(m, d) - K(m + 1)$$

except for the following cases:

- $d = 2$ and $2 \leq K \leq m$
- $d \geq 3$ and $(m, d, K) \in \{(2, 4, 5), (3, 4, 9), (4, 1, 14), (4, 3, 7)\}$

In other words, there are a *finite number* of exceptions.

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- Thalès Communications